

PSL in HolCheck

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HolCheck

- symbolic model checker embedded in the HOL theorem prover
- all steps of the algorithm are proved in HOL
- based on *HolBdd* developed by Mike Gordon
- developed at the ARG, mainly by Hasan Amjad
- supports μ -calculus and CTL

Overview

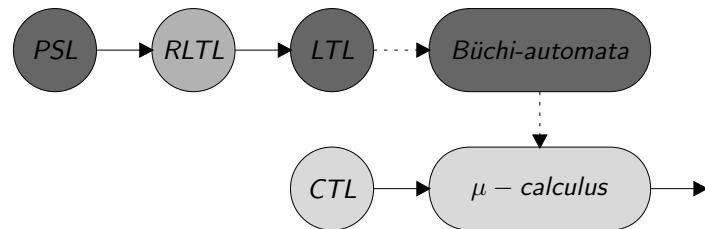
- 1 Motivation
 - HolCheck
 - *PSL*
 - Integration of *PSL* into *HolCheck*
- 2 Used Formalisms
 - Linear Temporal Logic (*LTL*)
 - Reset Linear Temporal Logic (*RLTL*)
 - Accellera's Property Specification Language (*PSL*)
 - Generalised Büchi Automata
- 3 Translation of a subset of *PSL* to Generalised Büchi Automata
- 4 Work
- 5 Conclusions

PSL

- many different formalisms for specifications exists like
 - *LTL*
 - *CTL*
 - *CTL**
 - ω -automata
 - monadic second order logics
 - μ -calculus
- **Accellera's Property Specification Language (*PSL*)** is a standardised industrial-strength property specification language
 - Version 1.0: April 2003
 - Version 1.1: June 2004
- *PSL* is quite similar to *ForSpec* Temporal Logic (*FTL*) presented by Moshe Vardi last week

Integration of *PSL* into *HolCheck*

- in my diploma thesis I formally validated a translation of a significant subset of *PSL* to generalised Büchi automata
- the emptiness problem of generalised Büchi automata remains
- this problem can be easily translated to a μ -calculus formula
- *HolCheck* is able to handle μ -calculus formulas



Linear Temporal Logic (*LTL*)

- introduced by Pnueli in 1977
- essentially consists of propositional logic enriched with temporal operators **X** and **U**
- for $w : \mathbb{N} \rightarrow 2^P$ the semantics is given by:
 - the usual semantics of propositional operators
 - $w \models p$ iff $p \in w^0$
 - $w \models \mathbf{X}\varphi$ iff $w^{1..} \models \varphi$
 - $w \models \varphi \mathbf{U}\psi$ iff φ holds on w until ψ holds and ψ eventually holds
- additional operators are added as syntactic sugar, e. g. **G**, **F**

Linear Temporal Logic (*LTL*) II

Example

The *LTL* formula

$$\mathbf{G}(\text{req} \rightarrow \mathbf{F}\text{ack})$$

specifies, that every request (req) has to be followed by an acknowledge (ack).

Reset Linear Temporal Logic (*RLTL*)

- *RLTL* is an extension of *LTL* with reset operators
- these operators are used to model hardware resets
- introduced by Armoni, Bustan, Kupferman and Vardi (TACAS 2003):
 - abort in *PSL* 1.0 leads to non-elementary blowup
 - ⇒ abort changed according to *RLTL* in *PSL* 1.1
- *RLTL* is as expressive as *LTL*
- translation of *RLTL* to *LTL* known
- unsurprisingly a significant subset of *PSL* 1.1 can be translated to *RLTL*

Reset Linear Temporal Logic (*RLTL*) II

Example

$G((req \rightarrow F ack) \text{ ACCEPT } cancel)$

specifies, that every request (*req*) has to be followed by an acknowledge (*ack*), unless a cancellation (*cancel*) occurs.

Accellera's Property Specification Language (*PSL*)

- *PSL* is an industrial strength property specification language
- *PSL* is based on IBM's *sugar* and Intel's *FTL* language
- *PSL* consists of different layers and different flavours
- here only the temporal layer is considered
- the temporal layer consists of
 - the *Foundation Language*
 - the *Optional Branching Extension*, which is essentially *CTL*

Accellera's Property Specification Language (*PSL*) II

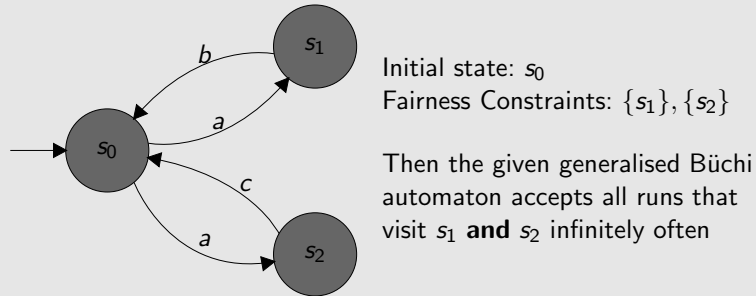
- the foundation language (*FL*) consists of
 - **linear temporal logic operators**
 - **reset operators**
 - clocking operators
 - regular expressions (*SEREs*)
 - a lot of syntactic sugar
- the semantics of *FL* consider finite and **infinite** paths
- we consider a significant subset of *FL* called *SUFL*, that consists of
 - linear temporal logic operators
 - reset operators
- we consider only infinite paths
- i. e. **we consider *FL* without regular expressions for model checking**

Generalised Büchi Automata

- generalised Büchi automata are finite automata on infinite words
- as the input is infinite, there is no last state of a run
- thus, the acceptance condition has to be defined somehow different
- a input is accepted by a generalised Büchi automaton, iff there is a run that visits some sets of states infinitely often
- these sets of states are called *fairness constraints*

Generalised Büchi Automata II

Example



Translation of *SUFL* to *RLTL*

- translation quite easy: replace every *PSL* operator with the corresponding *RLTL* operator
- however, correctness proof tricky
- the semantics of *SUFL* is given using special states \top, \perp
- in contrast *RLTL* uses acceptance / rejection conditions
- these concepts have to be mapped to each other
- a lot of technical problems occur

Translation of *RLTL* to Generalised Büchi Automata

Translation of *RLTL* to *LTL*

- translation given by Armoni, Bustan, Kupferman and Vardi
- consists of simple rewrite rules
- correctness proof straightforward

Translation of *LTL* to Generalised Büchi Automata

- translation is well known
- we use a symbolic representation of ω -automata
- translation can be done in linear time with respect to the size of the *LTL* formula

Overall Model Checking Procedure

- given a kripke structure M and a *SUFL* formula f the problem is to check whether all paths through M satisfy f
- translate $\neg f$ to a generalised Büchi automaton A
- build the product $M \times A$ of M and A
- check whether there exists a fair path through $M \times A$
- this emptiness check can be expressed in μ -calculus or in *FairCTL*
- use *HolCheck* to evaluate this μ -calculus formula

Work done in *HOL*

- we used Mike Gordon's deep embedding of *PSL*
- we deeply embedded:
 - *RLTL*
 - *LTL*
 - automaton formulas, a symbolic representation of nondeterministic ω -automata
- we formally verified:
 - the translation of *PSL* to *RLTL*
 - a translation of *RLTL* to *LTL*
 - a translations of *LTL* to automaton formulas

Current Work

- refactoring
- optimising the translation of *LTL* to automaton formulas
- translation of generalised Büchi automata to μ -calculus
- implementing interfaces to *HolCheck*

Possible Future Work

- adding *FairCTL*, *CTL** and ω -automata as input languages to *HolCheck*
- extending the subset of *PSL* to full *FL*
- we are already able to translate *LTL* safety properties to alternation free μ -calculus
- add a specialised translation of *LTL* liveness properties to alternation free μ -calculus
- ...

Conclusions

- *PSL* is an important specification language
- *SUFL* is a significant subset of *PSL*
- we translated *SUFL* to *RLTL* and further to *LTL* and generalised Büchi automata
- we deeply embedded *LTL*, *RLTL* and automaton formulas
- we will soon be able to use *SUFL* and *LTL* as input languages for *HolCheck*